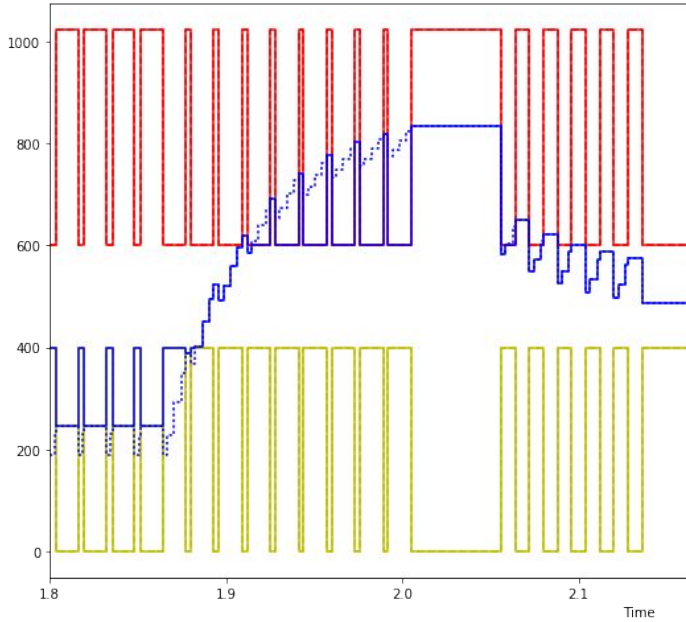
UtilClamp

Status update on Utilization Clamping support

for FAIR and RT tasks



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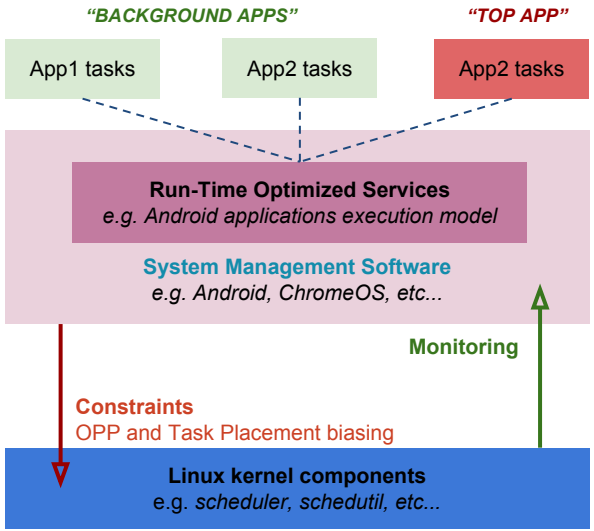
Introduction

What is the problem on hand?

*Feed **context aware** information about **tasks requirements***
*from **System Management Software (SMS)** to kernel-space*
*to **improve existing policies** for **OPPs selections** and **TASKs placement***



The **utilization** is already used in many decisions

- by schedutil to drive **OPP selection**
- by the (EA)Scheduler for **task placement**

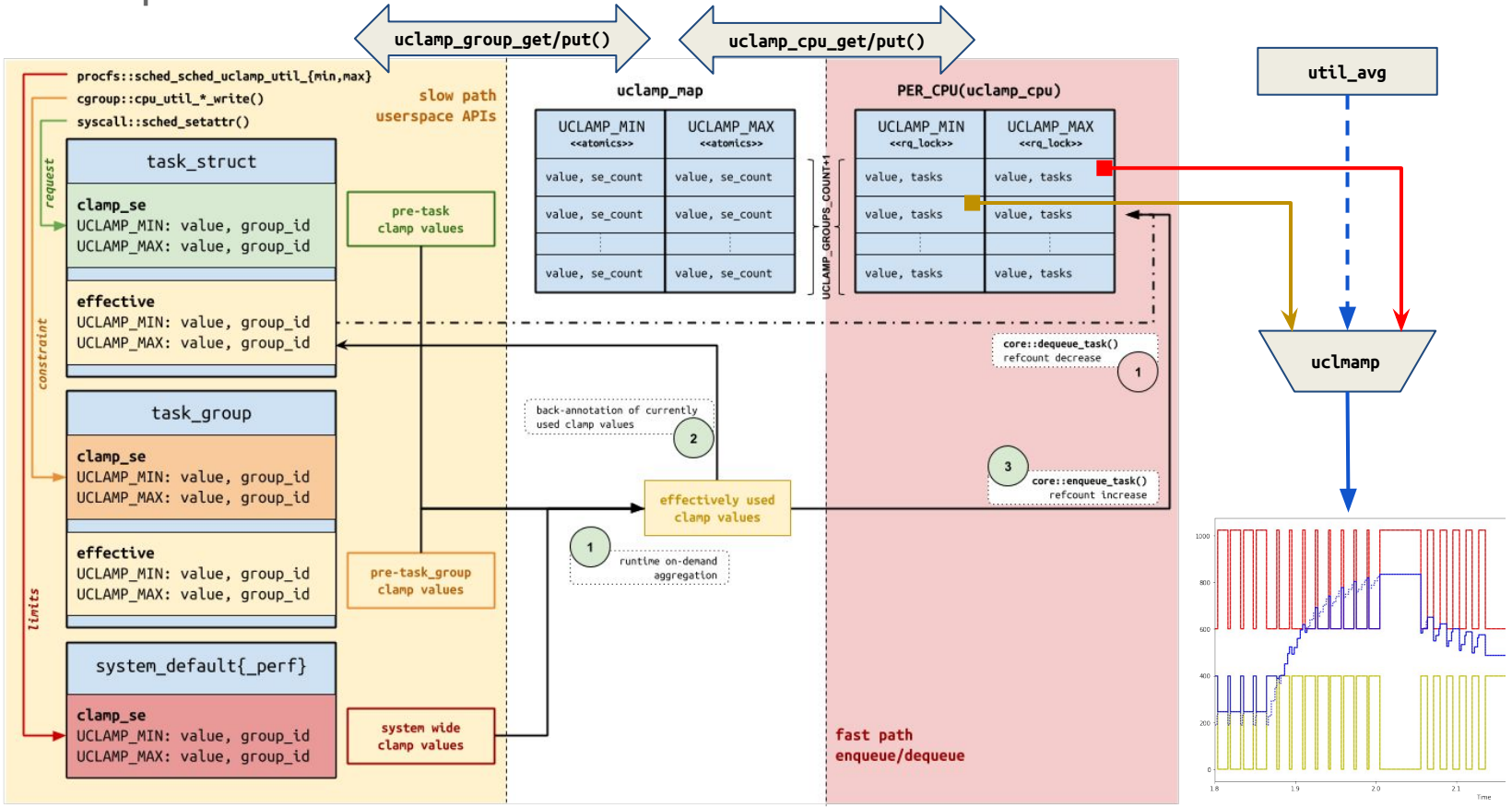
We are looking for a **per-task{group}** API

- **clamp** the utilization of each task
- **aggregate** the clamped utilization of RUNNABLE tasks on each CPU

https://goo.gl/a1i7VH [1]

Proposal

UtilClamp v5[1] in a Nutshell



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Main Discussion Points (1/3)

Are we heading in the right direction?

Is **bucketization** acceptable?

- user-space requests always mapped into a finite number of clamp groups
  - configured at compile time, e.g. 10-20, as a linear sub-division of the max capacity
- from use-cases on hand we do not expect many different boost/clamp values
  - clamp groups mapping ensure to use only the minimum number of clamp groups actually required

Are **system defaults** acceptable?

- system_default clamps for FAIR tasks, restrict task-specific and task group clamps
  - exposed as (root only writable) /proc/sys/kernel/sched_uclamp_util_{min,max}
  - by default: util_min=0 and util_max=SCHED_CAPACITY_SCALE
- system_default_perf clamps for RT task
  - by default: util_min=util_max=SCHED_CAPACITY_SCALE

Is clamping **acceptable for RT** tasks?

- entirely optional framework, no overheads on !CONFIG_UCLAMP_TASK
- even when compiled in, system_default_perf defaults to always running at max freq
  - still allows to improve energy efficiency for certain RT tasks on mobile systems

Main Discussion Points (2/3)

How far are we?

Is the **effective** aggregation acceptable?

- scheduler: compute the actual clamp value at enqueue time
  - a caching mechanism is possible if we should consider that an overhead
- cgroups: transparently track the most restrictive clamp between a group and its parent
  - subgroups can always change their clamps
  - hierarchical updates ensure to always propagate and use the max value

What's the best **merging** strategy?

- keep refining core bits and merge those before cgroup integration...
  - risk of data structures not suitable for a smooth integration in the cpu controller
- ... or update the full patchset until both core bits and cgroup support are ACKed?
  - safer solution but will required more time

Main Discussion Points (3/3)

What are possible future extensions?

Add a **timer-based release** semantic ?

- event-based clamp set, timeout-based clamp reset
  - touchboost is an example use-case already used in Android
- it can potentially be used to implement features like the **iowait boost**
  - with the advantage of being a the per-task / user-space defined hint

Add a **generic kernel-space API** to access clamp groups ?

- drivers and/or firmware can be interested in asserting clamp values
- we can take advantage of a unified and well defined interface to aggregate user/kernel-space clamps
  - kernel-space clamps can provide a restriction to user-space clamps
  - which aggregation policy makes sense will be defined by a single “framework”
- kind-of similar to **pm_qos** but more cpu and task specific and limited to clamp values
  - maybe it could make sense to just add util clamp metrics to pm_qos?

Thanks for the discussion

That's all... for Today

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